

## Yoonchang Sung

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### Education

#### Virginia Tech, Blacksburg, USA

Ph.D. in Electrical & Computer Engineering, September 2014–Present  
Advisor: Pratap Tokekar

#### Korea University, Seoul, Korea

M.S. in Mechanical Engineering, August 2013  
Advisor: Woojin Chung

#### Korea University, Seoul, Korea

B.S. in Mechanical Engineering, February 2011

### Employment

#### Research Assistant, September 2016–Present

Dept. of Electrical & Computer Engineering, Virginia Tech, Blacksburg, USA  
Advisor: Pratap Tokekar

#### Research Assistant, September 2014–August 2016

Dept. of Mechanical Engineering, Virginia Tech, Blacksburg, USA  
Advisor: Brian Lattimer & Tomonari Furukawa

#### Research Intern, August 2013–June 2014

Center for Bionics, Korea Institute of Science and Technology, Seoul, Korea  
Supervisor: JongSuk Choi

#### Research Assistant, March 2011–August 2013

Dept. of Mechanical Engineering, Korea University, Seoul, Korea  
Advisor: Woojin Chung

### Teaching

#### Teaching Assistant

Dept. of Mechanical Engineering, Korea University, Seoul, Korea  
MECH 210: Computer Aided Mechanical Drawing, Spring 2012  
MECH 328: Machine Component Design, Fall 2011

Dept. of Electrical & Computer Engineering, Virginia Tech, Blacksburg, USA  
ECE 4984: SS:Robot Motion Planning, Guest Lecturer: Introduction to ROS, August 2018

### Publications

#### Journal Articles

*Under Review*

[J5] Z. Zhang, J. Lee, JM Smereka, **Y. Sung**, L. Zhou, and P. Tokekar, “Tree search techniques for minimizing detectability and maximizing visibility,” *IEEE Robotics and Automation Letters (RA-L)*, Note: Submitted.

[J4] **Y. Sung**, AK Budhiraja, RK Williams, and P. Tokekar, “Distributed simultaneous action and target assignment for multi-robot multi-target tracking,” *Autonomous Robots (AuRo)*, Note: Submitted.

[J3] **Y. Sung**, and P. Tokekar, “GM-PHD filter for searching and tracking an unknown number of targets with a mobile sensor with limited FoV,” *IEEE Transactions on Automation Science and Engineering (T-ASE)*, Note: Submitted.

*Published*

[J2] C. Knabe, R. Griffin, J. Burton, G. Cantor-Cooke, L. Dantanarayana, G. Day, O. Ebeling-Koning, E. Hahn, M. Hopkins, J. Neal, J. Newton, C. Nogales, V. Orekhov, J. Peterson, M. Rouleau, J. Seminatore, **Y. Sung**, J. Webb, N. Wittenstein, J. Ziglar, A. Leonessa, B. Lattimer, and T. Furukawa, “Team VALOR’s ESCHER: A novel electromechanical biped for the DARPA Robotics Challenge,” *Journal of Field Robotics (JFR)*, 34(5): pp. 912-939, 2017.

[J1] **Y. Sung**, and W. Chung, “Hierarchical sample-based joint probabilistic data association filter for following human legs using a mobile robot in a cluttered environment,” *IEEE Transactions on Human-Machine Systems (T-HMS)*, 46(3): pp. 340-349, 2016.

## Refereed Conference Publications

*Under Review*

[C9] **Y. Sung**, and P. Tokekar, “A competitive algorithm for online multi-robot exploration of a translating plume,” *IEEE International Conference on Robotics and Automation (ICRA 2019)*, Note: Submitted.

*Published*

[C8] **Y. Sung**, AK Budhiraja, RK Williams, and P. Tokekar, “Distributed simultaneous action and target assignment for multi-robot multi-target tracking,” *IEEE International Conference on Robotics and Automation (ICRA 2018)*, 2018. Note: To Appear.

[C7] **Y. Sung**, and P. Tokekar, “Hierarchical GM-PHD filter for false alarm reduction in search and tracking task,” *US-KOREA Conference on Science, Technology and Entrepreneurship (UKC 2017)*, 2017.

[C6] **Y. Sung**, and P. Tokekar, “Algorithms for searching and tracking an unknown and varying number of mobile targets using a limited FoV sensor,” *IEEE International Conference on Robotics and Automation (ICRA 2017)*, 2017.

[C5] JH Kim, **Y. Sung**, and B. Lattimer, “Bayesian estimation based real-time fire-heading in smoke-filled indoor environments using thermal imagery,” *IEEE International Conference on Robotics and Automation (ICRA 2017)*, 2017.

[C4] **Y. Sung**, and T. Furukawa, “Information measure for the optimal control of target searching via the grid-based method,” *International Conference on Information Fusion (Fusion 2016)*, 2016.

[C3] B. Lattimer, J. Starr, J. McNeil, C. Nogales, J. Peterson, J. Ziglar, J. Burton, C. Knabe, **Y. Sung**, J. Seminatore, R. Griffin, J. Newton, V. Orekhov, M. Rouleau, M. Hopkins, D. Hong, and D. Lee, “Humanoid firefighting robot for structure fires,” *International Conference and Exhibition on Fire Science and Engineering (Interflam 2016)*, 2016.

[C2] D. Cha, H. Cho, J. Jin, H. Kwon, J. Kim, H. Lee, J. Seong, C. Moon, H. Kim, **Y. Sung**, and W. Chung, “Tracking human legs for an indoor mobile robot with a single laser range finder,” *International Conference on Engineering and Applied Sciences (ICEAS 2015)*, 2015.

[C1] **Y. Sung**, and W. Chung, “Human tracking of a mobile robot with an onboard LRF(Laser Range Finder) using human walking motion analysis,” *International Conference on Ubiquitous Robots and Ambient Intelligence (URAI 2011)*, 2011.

### **Refereed Workshop Publications**

[W2] **Y. Sung**, S. Buebel, and P. Tokekar, “Detecting and mapping hazardous plumes with aerial and surface robots,” *IEEE International Conference on Robotics and Automation (ICRA 2018) Workshop on Robot Teammates Operating in Dynamic, Unstructured Environment*, 2018.

[W1] **Y. Sung**, AK Budhiraja, RK Williams, and P. Tokekar, “Distributed simultaneous action and target assignment for multi-robot multi-target tracking,” *IEEE International Conference on Robotics and Automation (ICRA 2017) Workshop on Multi-robot Perception-driven Control and Planning*, 2017.

### **Book Chapters**

[B1] C. Knabe, R. Griffin, J. Burton, G. Cantor-Cooke, L. Dantanarayana, G. Day, O. Ebeling-Koning, E. Hahn, M. Hopkins, J. Neal, J. Newton, C. Nogales, V. Orekhov, J. Peterson, M. Rouleau, J. Seminatore, **Y. Sung**, J. Webb, N. Wittenstein, J. Ziglar, A. Leonessa, B. Lattimer, and T. Furukawa, “Team VALOR’s ESCHER: A Novel Electromechanical Biped for the DARPA Robotics Challenge,” *The DARPA Robotics Challenge Finals: Humanoid Robots To The Rescue*. Springer, Cham., pp. 583-629, 2018.

### **Posters**

[P1] **Y. Sung**, and W. Chung, “Implementation of JPDAFs to track humans for a mobile robot with a laser range finder,” *IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN 2013)*, 2013.

### **Patents**

**Y. Sung**, and W. Chung, “Leg tracking method based on SJPDAF method,” Korean Domestic Patent (No. 10-1573620)

## **Honors**

### **Awards**

Conference Travel Awards: ICRA 2017, ICRA 2018  
DARPA Robotics Challenge (DRC) Finalist, 2015

### **Graduate Fellowship**

Research Assistant Scholarships, Virginia Tech, Blacksburg, USA, Fall 2014–Present  
The Welfare Section Scholarship, Korea University, Seoul, Korea, Fall 2012, Spring 2012

The Second Stage of BK21 Scholarship, Korea University, Seoul, Korea, Spring 2011  
Research Assistant Scholarships, Korea University, Seoul, Korea, Fall 2011

### **Undergraduate Fellowship**

Best Honors Scholarships, Korea University, Seoul, Korea, Spring 2010  
Honors Scholarships, Korea University, Seoul, Korea, Fall 2010, Spring 2009, Fall 2008  
National Science Scholarship, Korea University, Seoul, Korea, Fall 2009

*References Available Upon Request (Last updated: Sep 16, 2018)*